EXERCISES

- 1. Verify the linearity and nonlinearity of the eight examples of PDEs given in the text, by checking whether or not equations (3) are valid.
- 2. Which of the following operators are linear?
 - (a) $\mathcal{L}u = u_x + xu_y$
 - (b) $\mathcal{L}u = u_x + uu_y$
 - (c) $\mathcal{L}u = u_x + u_y^2$
 - (d) $\mathcal{L}u = u_x + u_y + 1$
 - (e) $\mathcal{L}u = \sqrt{1 + x^2} (\cos y)u_x + u_{yxy} [\arctan(x/y)]u_x$
- 3. For each of the following equations, state the order and whether it is nonlinear, linear inhomogeneous, or linear homogeneous; provide reasons.
 - (a) $u_t u_{xx} + 1 = 0$
 - (b) $u_t u_{xx} + xu = 0$
 - (c) $u_t u_{xxt} + uu_x = 0$
 - (d) $u_{tt} u_{xx} + x^2 = 0$

 - (d) $u_{tt} u_{xx} + u/x = 0$ (e) $u_t u_{xx} + u/x = 0$ (f) $u_x (1 + u_x^2)^{-1/2} + u_y (1 + u_y^2)^{-1/2} = 0$
 - (g) $u_x + e^y u_y = 0$
 - (h) $u_t + u_{xxxx} + \sqrt{1+u} = 0$
- 4. Show that the difference of two solutions of an inhomogeneous linear equation $\mathcal{L}u = g$ with the same g is a solution of the homogeneous equation $\mathcal{L}u = 0$.
- 5. Which of the following collections of 3-vectors [a, b, c] are vector spaces? Provide reasons.
 - (a) The vectors with b = 0.
 - (b) The vectors with b = 1.
 - (c) The vectors with ab = 0.
 - (d) All the linear combinations of the two vectors [1, 1, 0] and [2, 0, 1].
 - (e) All the vectors such that c - a = 2b.
- 6. Are the three vectors [1, 2, 3], [-2, 0, 1], and [1, 10, 17] linearly dependent or independent? Do they span all vectors or not?
- 7. Are the functions 1 + x, 1 x, and $1 + x + x^2$ linearly dependent or independent? Why?
- 8. Find a vector that, together with the vectors [1, 1, 1] and [1, 2, 1], forms a basis of \mathbb{R}^3 .
- 9. Show that the functions $(c_1 + c_2 \sin^2 x + c_3 \cos^2 x)$ form a vector space. Find a basis of it. What is its dimension?
- Show that the solutions of the differential equation u''' 3u'' + 4u = 010. form a vector space. Find a basis of it.
- 11. Verify that u(x, y) = f(x)g(y) is a solution of the PDE $uu_{xy} = u_x u_y$ for all pairs of (differentiable) functions f and g of one variable.

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12. Verify by direct substitution that

$$u_n(x, y) = \sin nx \sinh ny$$

is a solution of $u_{xx} + u_{yy} = 0$ for every n > 0.

1.2 FIRST-ORDER LINEAR EQUATIONS

We begin our study of PDEs by solving some simple ones. The solution is quite geometric in spirit.

The simplest possible PDE is $\partial u/\partial x = 0$ [where u = u(x, y)]. Its general solution is u = f(y), where f is any function of *one* variable. For instance, $u = y^2 - y$ and $u = e^y \cos y$ are two solutions. Because the solutions don't depend on x, they are constant on the lines y = constant in the xy plane.

THE CONSTANT COEFFICIENT EQUATION

Let us solve

$$au_x + bu_y = 0, (1)$$

where a and b are constants not both zero.

Geometric Method The quantity $au_x + bu_y$ is the directional derivative of u in the direction of the vector $\mathbf{V} = (a, b) = a\mathbf{i} + b\mathbf{j}$. It must always be zero. This means that u(x, y) must be constant in the direction of \mathbf{V} . The vector (b, -a) is orthogonal to \mathbf{V} . The lines parallel to \mathbf{V} (see Figure 1) have the equations bx - ay = constant. (They are called the *characteristic lines*.) The solution is constant on each such line. Therefore, u(x, y) depends on bx - ay only. Thus the solution is

$$u(x, y) = f(bx - ay),$$
(2)

where *f* is any function of one variable. Let's explain this conclusion more explicitly. On the line bx - ay = c, the solution *u* has a constant value. Call



Figure 1

uniqueness). It is also unstable. To illustrate the instability further, consider a nonsingular matrix A with one very small eigenvalue. The solution is unique but if b is slightly perturbed, then the error will be greatly magnified in the solution u. Such a matrix, in the context of scientific computation, is called ill-conditioned. The ill-conditioning comes from the instability of the matrix equation with a singular matrix.

As a fourth example, consider Laplace's equation $u_{xx} + u_{yy} = 0$ in the region $D = \{-\infty < x < \infty, 0 < y < \infty\}$. It is *not* a well-posed problem to specify both u and u_y on the boundary of D, for the following reason. It has the solutions

$$u_n(x, y) = \frac{1}{n} e^{-\sqrt{n}} \sin nx \sinh ny.$$
⁽²⁾

Notice that they have boundary data $u_n(x, 0) = 0$ and $\partial u_n / \partial y(x, 0) = e^{-\sqrt{n}} \sin nx$, which tends to zero as $n \to \infty$. But for $y \neq 0$ the solutions $u_n(x, y)$ do not tend to zero as $n \to \infty$. Thus the stability condition (iii) is violated.

EXERCISES

1. Consider the problem

$$\frac{d^2u}{dx^2} + u = 0$$

 $u(0) = 0$ and $u(L) = 0$,

consisting of an ODE and a pair of boundary conditions. Clearly, the function $u(x) \equiv 0$ is a solution. Is this solution *unique*, or not? Does the answer depend on *L*?

2. Consider the problem

$$u''(x) + u'(x) = f(x)$$

$$u'(0) = u(0) = \frac{1}{2}[u'(l) + u(l)],$$

with f(x) a given function.

- (a) Is the solution *unique*? Explain.
- (b) Does a solution necessarily *exist*, or is there a condition that f(x) must satisfy for existence? Explain.
- 3. Solve the boundary problem u'' = 0 for 0 < x < 1 with u'(0) + ku(0) = 0and $u'(1) \pm ku(1) = 0$. Do the + and - cases separately. What is special about the case k = 2?
- 4. Consider the Neumann problem

$$\Delta u = f(x, y, z) \quad \text{in } D$$
$$\frac{\partial u}{\partial n} = 0 \quad \text{on bdy } D.$$

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- (a) What can we surely add to any solution to get another solution? So we don't have uniqueness.
- (b) Use the divergence theorem and the PDE to show that

$$\iiint\limits_{D} f(x, y, z) \, dx \, dy \, dz = 0$$

is a necessary condition for the Neumann problem to have a solution.

- (c) Can you give a physical interpretation of part (a) and/or (b) for either heat flow or diffusion?
- 5. Consider the equation

$$u_x + yu_y = 0$$

with the boundary condition $u(x, 0) = \phi(x)$.

- (a) For $\phi(x) \equiv x$, show that no solution exists.
- (b) For $\phi(x) \equiv 1$, show that there are many solutions.
- 6. Solve the equation $u_x + 2xy^2u_y = 0$.

1.6 TYPES OF SECOND-ORDER EQUATIONS

In this section we show how the Laplace, wave, and diffusion equations are in some sense typical among all second-order PDEs. However, these three equations are quite different from each other. It is natural that the Laplace equation $u_{xx} + u_{yy} = 0$ and the wave equation $u_{xx} - u_{yy} = 0$ should have very different properties. After all, the *algebraic* equation $x^2 + y^2 = 1$ represents a circle, whereas the equation $x^2 - y^2 = 1$ represents a hyperbola. The parabola is somehow in between.

In general, let's consider the PDE

$$a_{11}u_{xx} + 2a_{12}u_{xy} + a_{22}u_{yy} + a_1u_x + a_2u_y + a_0u = 0.$$
 (1)

This is a linear equation of order two in two variables with six real constant coefficients. (The factor 2 is introduced for convenience.)

Theorem 1. By a linear transformation of the independent variables, the equation can be reduced to one of three forms, as follows.

(i) *Elliptic case:* If $a_{12}^2 < a_{11}a_{22}$, it is reducible to

$$u_{xx} + u_{yy} + \cdots = 0$$

(where \cdots denotes terms of order 1 or 0).

(ii) Hyperbolic case: If $a_{12}^2 > a_{11}a_{22}$, it is reducible to

$$u_{xx} - u_{yy} + \cdots = 0$$